

Positioning the H-Point Design Tool – Seating Reference Point and Seat Track Length

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Foreword

This practice describes how to position and posture the H-point design tool (HPD), and how to establish the seating reference point (SgRP) and other key reference points that are used in the design and specification of both driver and passenger seat positions. Use of the HPD in conjunction with the H-point machine (HPM) for benchmarking vehicle occupant packages is described in SAE J4003.

Prediction of where drivers select seat positions on the seat adjuster path is important for many aspects of vehicle design related to comfort and safety. Vehicle designers use driver seat position models to determine the length and location of adjustable seat tracks to insure that drivers of varying size can comfortably reach and operate vehicle hand and foot controls.

This document provides a new method for determining driver seat track length and for positioning the seat track in the vehicle package. It is based on studies and statistical models developed at the University of Michigan Transportation Research Institute. The new method for positioning driver seat tracks in the vehicle is based on H30 and two new variables, L6 and the presence or absence of a clutch pedal. The seat track length is independent of vehicle seat or package variables. It is based on accommodating with high statistical confidence the range of statures represented by an equal number of U.S. male and female drivers. Background details of the new method are given in Appendix A. Historical information about the prior procedure is given in Appendix C.

SAE J4004 will in the future fully replace SAE J1517:1990 for Class A vehicles. Until 2017 the ball-of-foot and accelerator heel point determined according to SAE J1517 may be used in lieu of the pedal reference point cited in this document. However, SAE J4004 should be used to determine the seat track length and the accommodation levels for the U.S. driving population.

1. Scope

This SAE Recommended Practice describes how to position and posture the H-point design tool (HPD) described in Appendix B, and how to establish the seating reference point (SgRP), design H-point travel path, and other key reference points that are used in the design and specification of both driver and passenger seat positions.

This practice also provides a method for determining the length of the seat track for a driver seat that adjusts fore/aft. The seat track length is based on a desired level of driver accommodation, assuming a U.S. population containing an equal number of male and female drivers. The procedure can be used to establish driver seat track accommodation for new vehicle designs or to evaluate accommodation in existing vehicles.

A general method for determining driver seat track length for any driver population (male and female stature distribution) at any selected accommodation percentile and gender mix is given in Appendix A.

Application of this Recommended Practice is limited to Class A Vehicles (Passenger Cars, Multipurpose Passenger Vehicles, and Light Trucks) as defined in SAE J1100.

1.1 Rationale

Not applicable.

2. References

2.1 Applicable Publications

This document contains provisions which reference the following documents. At the time of publication, the indicated editions of these references were valid. Since all publications are subject to revision or deletion, users of this document are encouraged to refer to the most recent published editions of these referenced documents. Information obtained using the following publications is needed for application of the procedures described in this Practice.

2.1.1 SAE PUBLICATIONS

Available from SAE, 400 Commonwealth Drive, Warrendale, PA 15096-001.

SAE J4002—H-Point Machine (HPM-II) Specifications and Procedure for H-Point Determination—
Auditing Vehicles Seats
SAE J1100—Motor Vehicle Dimensions—2005

2.2 Related Publications

The following publications were discussed or used to develop the seating accommodation procedures and are not required for application of this document:

SAE J4004 Issued AUG2005

2.2.1 SAE PUBLICATIONS

Available from SAE, 400 Commonwealth Drive, Warrendale, PA 15096-001.

SAE J826—Devices for Use in Defining and Measuring Vehicle Seating Accommodation

SAE J1516—Accommodation Tool Reference Point

SAE J1517—Driver Selected Seat Position

SAE J4003—Procedure for H-Point Determination—Benchmarking Vehicle Seats

2.2.2 Philippart, N.L., Roe, R.W., Arnold, A.J., and Kuechenmeister, T.J. (1984). *Driver selected seat position model*. SAE Technical Paper 840508. Society of Automotive Engineers, Inc., Warrendale, PA.

2.2.3 Flannagan, C.C., Schneider, L.W., and Manary, M.A. (1996). *Development of a Seating Accommodation Model*. SAE Technical Paper 960479. Society of Automotive Engineers, Inc., Warrendale, PA.

2.2.4 Abraham, S., Johnson, C.L., and Najjar, M.F. (1979). Weight and height of adults 18-74 years of age. *Vital and Health Statistics*. Series 11, No. 211.

2.2.5 U. S. National Health and Nutrition Examination Survey (NHANES III): Height for males and females 20 years and older: United States, 1988-1994.

2.2.6 Flannagan, C. C., Schneider, L.W., and Manary, M.A., and Reed, M. P. (1998). *An Improved seating Accommodation Model with Application to Different User Populations*. SAE Technical Paper 980651. Society of Automotive Engineers, Inc., Warrendale, PA.

3. Definitions

3.1 SAE J1100 Definitions (See Figure 1)

Pedal Reference Point (PRP)

Accelerator Heel Point (AHP)

Floor Reference Point (FRP)

H-point

Seating Reference Point (SgRP)

H-Point Travel Path

H30 – Seat Height

A27 – Cushion Angle

L6 – Pedal Reference Point (PRP) to Steering Wheel Center

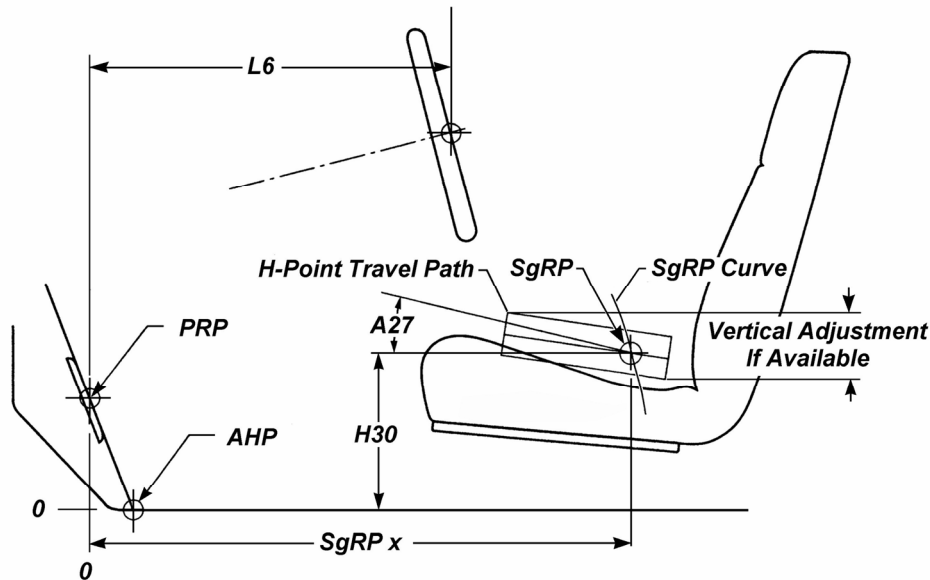


FIGURE 1—SEATING PACKAGE DESCRIPTION SHOWING PACKAGE FACTORS USED TO CALCULATE DRIVER SEAT POSITIONS

3.2 SAE J4004 Definitions

- 3.2.1 Driver Seat Position Accommodation – percent of a 50/50 male/female driver population whose preferred fore/aft seat track position is within the seat track travel path
- 3.2.2 Driver Seat Position Accommodation Point – point on design H-point travel path that provides a specified level of driver seat position accommodation for a given driver population and vehicle package

4. Determining the Driver Seating Reference Point and Positioning the HPD

This procedure is used to position the H-point design tool (HPD, Figure 2) in the correct location for the driver's position, and to establish the driver seating reference point (SgRP-Front), pedal reference point (PRP), and accelerator heel point (AHP). Specifications and tolerances for the HPD are given in Appendix B.

4.1 Overview of Design Procedures

The HPD is used during design to establish key reference points within the vehicle, including the SgRP for each occupant position, and heel points (accelerator heel point for the driver and floor reference points for passengers). These points are then used to configure and measure many aspects of the vehicle interior compartment.

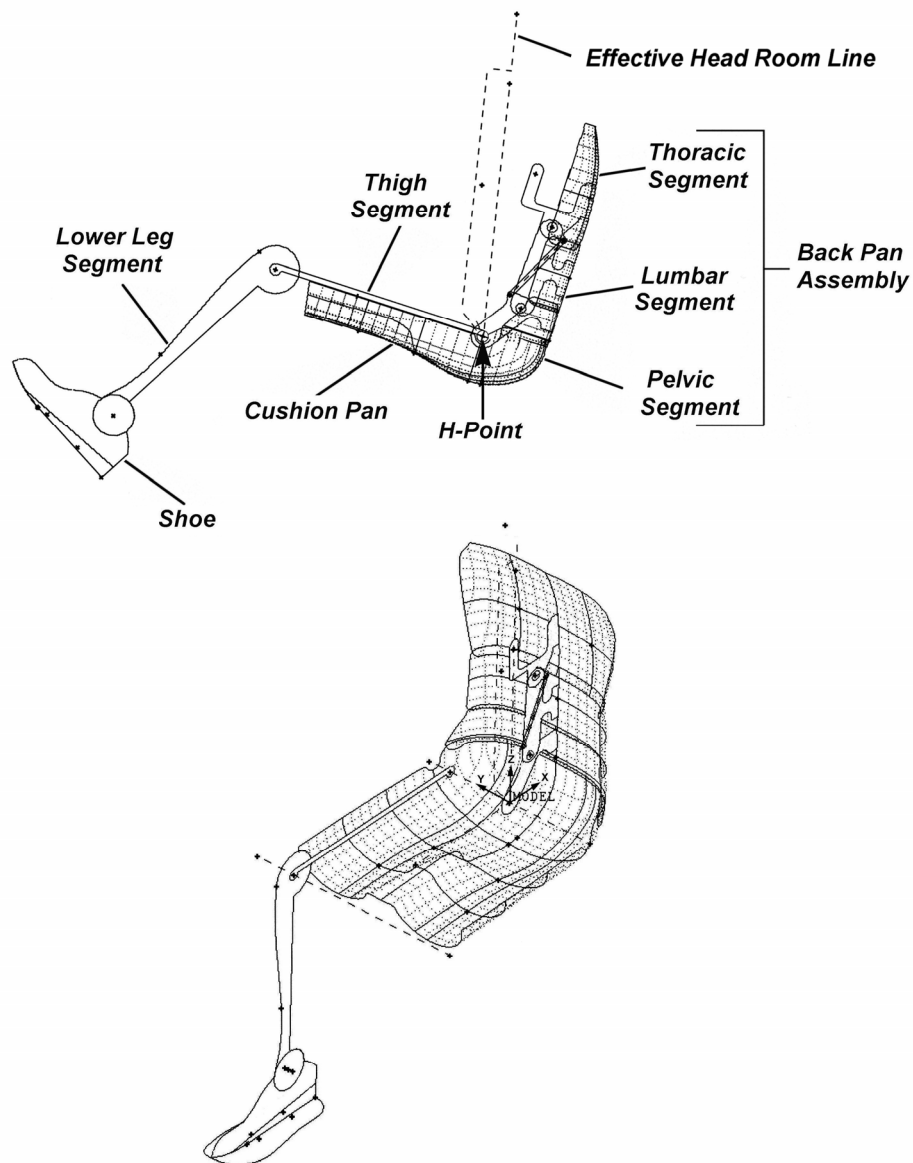


FIGURE 2—H-POINT DESIGN TOOL (HPD) - COMPONENTS COMMON WITH H-POINT MACHINE (HPM-II)

The SgRP is a specific and unique H-point location for a designated seating position. (Although adjustable seats will have many H-point locations within their H-point travel path, only one H-point location is defined as the SgRP for any designated occupant seating position.) The most critical SgRP is the one defined for the driver (SgRP-Front). It is used to position many other design tools (e.g., head contours, eyellipses), to define a number of key vehicle dimensions (e.g., legroom, shoulder room, etc.), and is cited in several national and international regulations and standards.

The accelerator pedal reference points established by this procedure, AHP and PRP, represent the design position of the accelerator pedal. Manufacturers may provide pedal adjustments in a vehicle to move the resting position of the pedals from their nominal design position. SAE J4004 does not provide methods for designing the travel path of these adjustable pedals.

4.2 Driver Designated Seating Position Design Procedure

4.2.1 DETERMINE THE INITIAL TARGET VALUES

Determine the initial target values for the dimensions listed in Table 1. (See SAE J1100 for definitions.) Some of these values may be modified during the procedure, resulting in different final values.

TABLE 1—VALUES FOR INITIAL POSITIONING OF THE HPD FOR DRIVER

Dimension	Code	Final Values
Seat Height	H30 _(Target)	The final value of H30 will be defined during this procedure.
Occupant Centerline	W20 _(Target)	If the seat track has an outboard/inboard angle, then the final value of W20 may be different than the target value (depending on the fore-aft location of SgRP).
Back (Torso) Angle	A40	Set at manufacturer design intent. A40 is a seat characteristic. It is neither calculated nor modified by this procedure. Rather, it is used to define the orientation of the back pan assembly.
Lumbar Support Prominence (LSP)	L81	L81 is a seat characteristic. It is neither calculated nor modified by this procedure. Rather, it is used to posture the back pan articulation, specifying the distance (X) of the lumbar-pelvic pivot (L/P pivot) to the back (torso) line, measured normal to the back line. (See Figure 3.) $LSP = 57 - X$ mm
Cushion Angle	A27	A27 is a seat characteristic. It is neither calculated nor modified by this procedure. It is used to position the attitude of the cushion pan assembly.

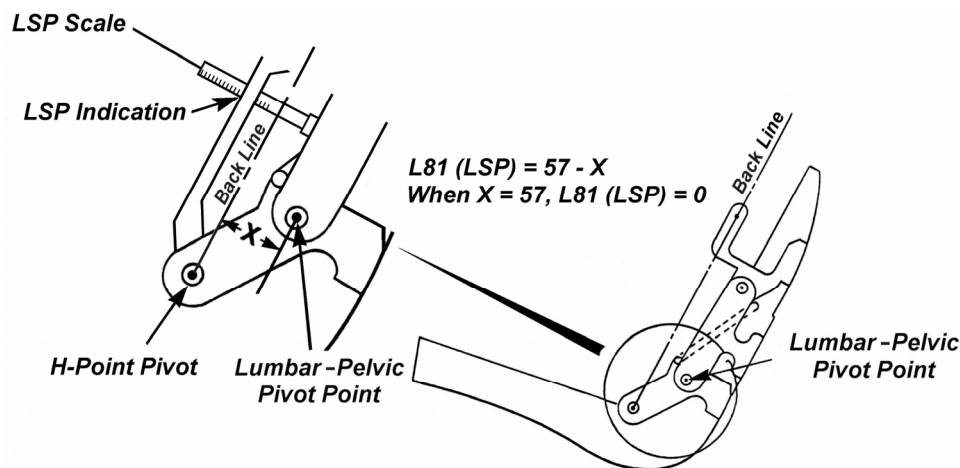


FIGURE 3—LUMBAR SUPPORT PROMINENCE (LSP)

4.2.2 DEFINE SHOE TOOL LOCATION AND ATTITUDE

The pedal plane angle defines the attitude of the shoe tool. Three methods are provided for calculating the pedal plane angle in order to position the shoe tool on the undepressed accelerator pedal. The pedal plane along with reference points on the shoe tool and pedal are shown in Figure 4.

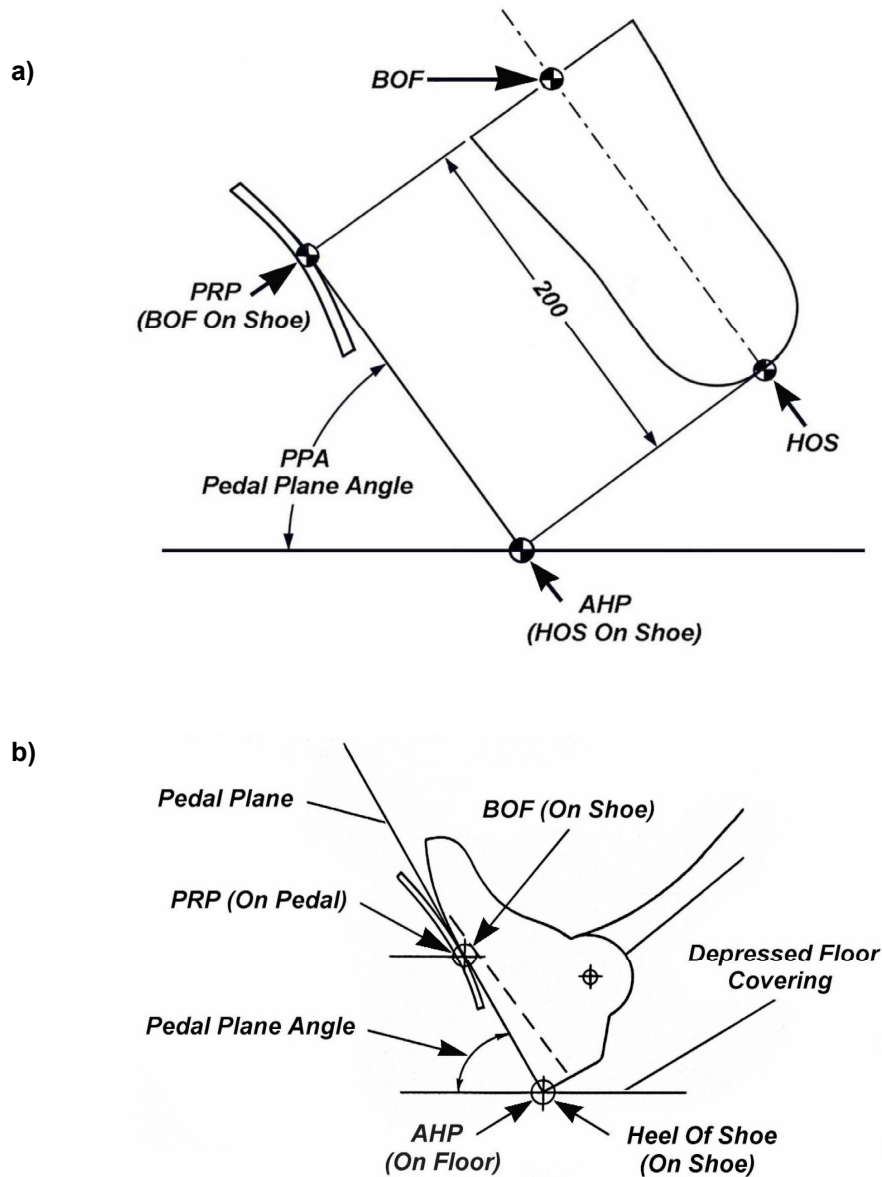


FIGURE 4—a) PEDAL PLANE CAD TOOL; b) SHOE REFERENCE POINTS

4.2.2.1 Define Pedal Plane Angle

The pedal plane and pedal plane angle are defined at the lateral centerline of the undepressed accelerator pedal. The pedal plane angle is measured from horizontal in side view, with the pedal in design position. In rear view, the segment from BOF to the heel of the shoe shall be vertical and square to grid (yaw is not permitted). If the accelerator pedal is angled in top view, align the pedal plane to the pedal (roll is permitted). The angle of this line from horizontal is the pedal plane angle.

If the pedal layout and geometry have not been defined yet, the pedal plane angle can be established using the alpha equation (Equation 1) in 4.2.2.1.1.

If the accelerator pedal has already been designed, there are two options for determining pedal plane angle:

- Use the accelerator geometry to determine pedal plane angle (4.2.2.1.2.).
- Use the pedal plane angle from the previous design (4.2.2.1.3).

4.2.2.1.1 Pedal Plane Angle from Alpha (α) Equation: Pedal Design

The alpha equation is provided to assist in pedal design, where:

$$\alpha = 77 - 0.08(H30) \text{ degrees from horizontal} = \text{pedal plane angle} \quad (\text{Eq. 1})$$

Design the pedal such that the pedal plane angle equals alpha with the BOF tangent to the pedal at centerline and the heel of shoe contacting the depressed floor covering.

Initially, the $H30_{(\text{Target})}$ value is used. If the final H30 value is different, a new alpha value can be obtained by iteratively calculating α , H30, and $SgRP_{(x)}$ values. However, this is not necessary.

4.2.2.1.2 Pedal Plane Angle Derived from Accelerator Pedal Geometry

1. Flat pedal pad— Position the pedal plane CAD tool so the BOF tangents the longitudinal centerline of the pedal pad surface with the heel on the depressed floor covering. If the pedal surface is square to grid in top view, the shoe (and pedal plane) will be tangent to the entire pedal pad surface. The pedal plane angle is defined by the angle of the pedal pad. If the pedal pad pivots independently of the pedal arm, use equation 1 to establish the pedal plane angle.
2. Curved pedal pad— The pedal plane angle is determined using the pedal plane CAD tool shown in Figure 4. With the heel of shoe on the depressed floor covering, adjust the pedal plane tool along the depressed floor covering until the pedal plane is tangent to the longitudinal centerline of pedal's surface at the BOF point. In side view the angle of the pedal plane from horizontal is the pedal plane angle.

4.2.2.1.3 Pedal Plane Angle Retained from Carryover Pedal Design

A third method is provided to give manufacturers the option of retaining the pedal plane angle, AHP, and BOF from the carryover design. In this case the 2-d H-point template should be used in lieu of the HPD as the design tool (see SAE J826 and J1517). This is the least preferred method and will be eliminated in 2017. For most of these carryover designs the pedal plane angle was determined by the theta equation given in SAE J1516.

With this design method the ankle angle was often locked at 87 degrees, which for curved pedals may have resulted in the BOF not being on the pedal surface. However, users could chose to unlock the ankle angle in order to get the BOF on the curved pedal surface (an option permitted by SAE J1516).

For this method the BOF shall be the pedal reference point.

4.2.2.1.4 Interference

If there is interference from a center console, the contour of the tunnel, etc., that prevents the heel of shoe from being positioned at the same Y coordinate as the PRP, translate the AHP to the left until the shoe clears the interference (Figure 5). The lateral offset between AHP and PRP should be recorded (PW14). The lateral offset does not influence the positioning of the H-point. It is measured for tracking purposes only.

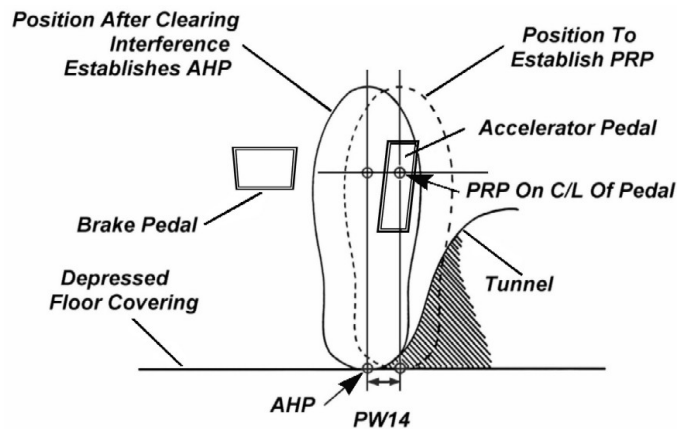


FIGURE 5—LATERAL OFFSET OF SHOE ON ACCELERATOR PEDAL (PW14)

4.2.2.2 Determine Coordinates for Shoe Reference Points

After the pedal plane is properly positioned the dimensions listed in Table 2 can be determined. When pedal plane is determined by Equation 1 or by pedal geometry, the pedal reference point (PRP) is the point on the lateral centerline of the accelerator pedal's surface contacted by the BOF. When the carryover pedal plane is used, the PRP is set at the BOF, which may not lie on the accelerator pedal surface. The AHP and PRP will have the same Y coordinate except when there is an interference condition.

TABLE 2—PEDAL REFERENCE POINTS AND DIMENSIONS (SEE SAE J1100 FOR DEFINITIONS)

Code	Name	Comment
A47	Pedal Plane Angle	
L1	PRP X Coordinate	Used for positioning SgRP curve
W1	PRP Y Coordinate	Centerline of accelerator pedal
H1	PRP Z Coordinate	
L8	AHP X Coordinate	
W8	AHP Y Coordinate	Optimally, W8=W1
H8	AHP Z Coordinate	Used to measure H30 (vertical distance between AHP and SgRP)
PW14	AHP to PRP Lateral Offset	

4.2.3 POSITION THE SGRP CURVE AND DESIGN H-POINT TRAVEL PATH

4.2.3.1 SgRP Curve (Figure 6)

The SgRP curve is positioned aft of the PRP using the following equation:

$$SgRP_x = 913.7 + 0.672316(H30) - 0.0019553(H30)^2 = \text{Distance (in mm) rearward of PRP} \quad (\text{Eq. 2})$$

This equation, which is the 95th-percentile accommodation curve from SAE J1517:1990, is used as the SgRP locating equation to provide consistency with previous industry practice.

The method for positioning the design H-point travel path through the SgRP is given in Section 5.

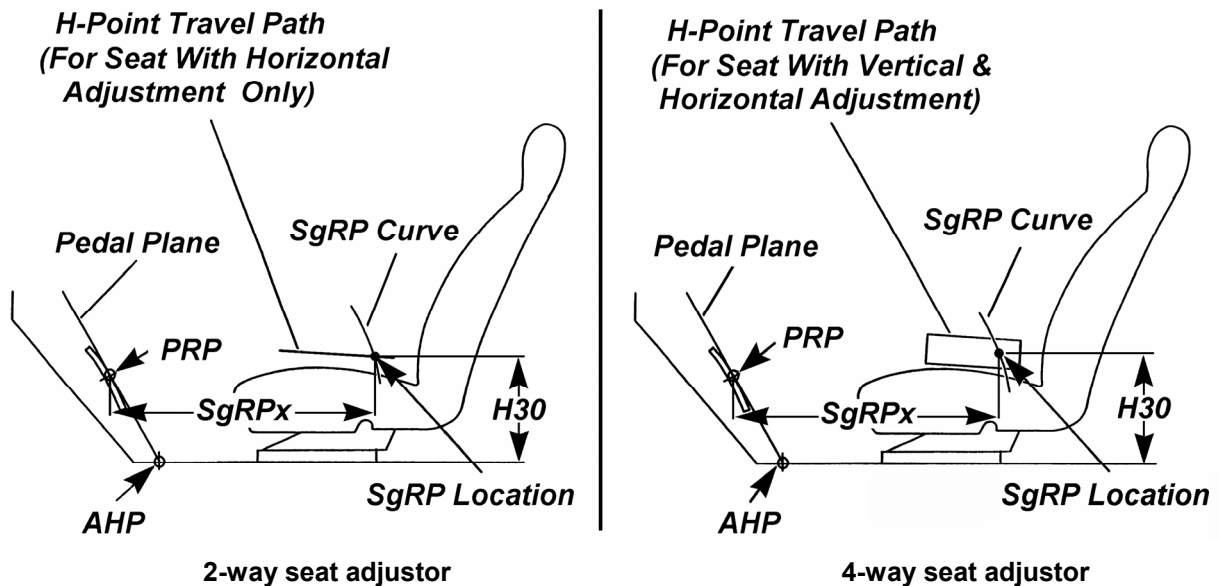


FIGURE 6—H-POINT TRAVEL PATHS, 2-WAY AND 4-WAY SEAT ADJUSTERS

4.2.4 DETERMINE SGRP, MEASURE H30, VERIFY W20

The vertical position of the SgRP along the SgRP curve is at the discretion of the manufacturer. For vertically adjustable seats, a recommended procedure for determining the SgRP is given in 4.2.4.2 and 4.2.4.3.

The vertical distance measured between the AHP and the SgRP is the design H30.

Depending on the x,z location of SgRP, W20 may be somewhat different than the initial $W20_{\text{Target}}$ value. This can happen when the track travel is not parallel to the longitudinal axis of the vehicle (i.e. the track travel is angled in plan view).

4.2.4.1 Fixed Seats

Since fixed seats have only one H-point location, this H-point is the SgRP. No further calculations are necessary.

1. Measure H30.
2. Verify W20.

4.2.4.2 Fore-aft Adjustable Seats Without Independent Height Adjustment

For seats without independent height adjustment, the H-point travel path can be described as a line (or curve). SgRP is the location where the SgRP curve intersects the design H-point travel path. (See Figure 6.)

1. Measure H30.
2. Verify W20.

4.2.4.3 Seats With Independent H-Point Fore-Aft and Height Adjustment

For seats with vertical and fore/aft adjustments, there are many points within the H-point travel path that lie on the SgRP curve. (See Figure 6.) The manufacturer has discretion in selecting which of the H-points along the SgRP curve is the SgRP. However, it is strongly recommended that the point at the middle of the vertical adjustment range be used.

4.2.4.3.1 Preferred Method

1. Determine the mid-height of the design H-point travel path.
2. Locate SgRP at the intersection of the SgRP curve and mid-height line of the design H-point travel path. (See Figure 7.)
3. Measure H30.
4. Verify W20.

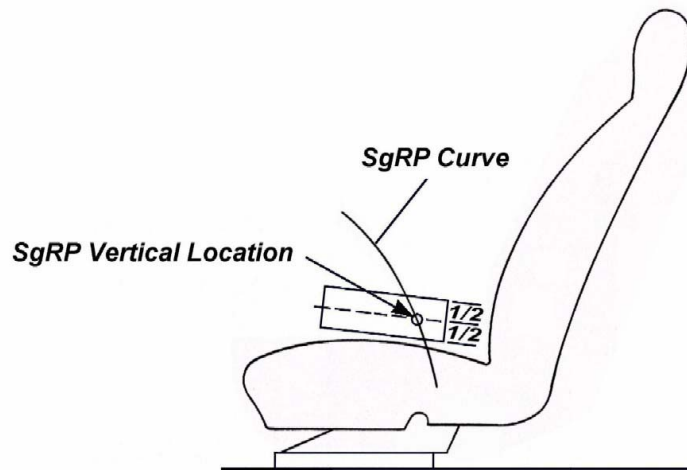


FIGURE 7—PREFERRED SGRP LOCATION IN A SEAT TRACK TRAVEL PATH WITH VERTICAL ADJUSTMENT

4.2.4.3.2 Alternative Method

1. Locate SgRP anywhere along the SgRP curve within the design H-point travel path.
2. Measure H30.
3. Verify W20.

4.2.4.4 Short Seat Track Travel

If the design H-point travel path is not long enough to include the SgRP determined by Equation 2, then the SgRP shall be defined and positioned at the rearmost point of the design H-point travel.

4.2.5 OPTIONAL ALPHA RECALCULATION

If pedal geometry was not available, and Equation 1 was used to define the pedal plane angle, the actual H30 determined in the previous steps may be different than the $H30_{\text{Target}}$ value. In this event, alpha may be recalculated. If alpha is recalculated, the locations of AHP and PRP will also change and need to be re-established. This will result in a different location for the SgRP curve, and a new H30. Steps 4.2.1 through 4.2.4 must be repeated.

4.2.6 POSITION HPD (CUSHION AND BACK PAN ASSEMBLIES)

Set the HPD H-point at SgRP with back (torso) angle at design intent, while maintaining the desired target values for cushion angle and lumbar support prominence (Figure 8). SAE J4004 does not provide methods for establishing design cushion angle, back angle, or LSP. These dimensions are determined by the manufacturer.

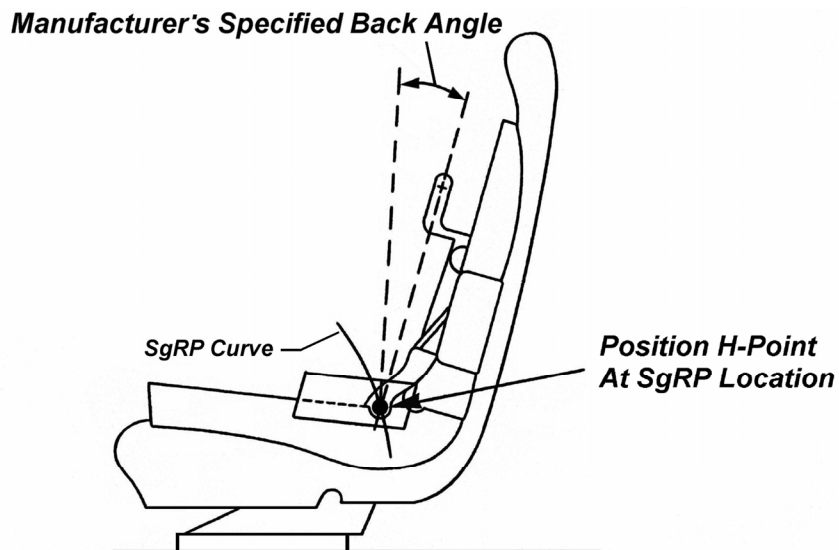


FIGURE 8—DESIGN BACK (TORSO) ANGLE OF HPD IS SET BY MANUFACTURER

4.2.7 POSITION HPD SHOE, THIGH, AND LOWER LEGS

Position the shoe tool so the flat area of the shoe, from ball of foot (BOF) to the heel of shoe, lies on the pedal plane, with the BOF aligned to the lateral centerline of the accelerator pedal, and the heel of shoe contacting the depressed floor covering. The accelerator heel point (AHP) is the point on the depressed floor covering that is contacted by the heel of shoe.

Use the SgRP leg lengths of 456 mm for thigh and 459 mm for lower leg. Position the legs without moving the shoe while keeping the H-point on the SgRP. The thigh rotates about the H-point y-axis connecting the H1L and H1R divot points, and the lower leg rotates about the ankle in order to accomplish this. The y-coordinate of the leg is aligned to the AHP y. Lateral splay of the leg is not permitted.

5. Driver Seat Track Accommodation for a U.S. Driver Population

5.1 Determine H-point Reference X Position

The x distance of the H-point reference position aft of the pedal reference point (PRP) is

$$\text{H-point reference position, } X_{\text{ref}} = 718 - 0.24(H30) + 0.41(L6) - 18.2t \quad (\text{Eq. 3})$$

where,

H30 is the vertical distance from the SgRP on the design H-point travel path to the AHP
 L6 is the PRP-to-steering wheel center, and
 t is the transmission type (1 if clutch pedal and 0 if no clutch pedal).

The Y and Z coordinates, W20 and H30, of the H-point reference position are determined by the manufacturer.

5.2 Determine Seat Track Length

The seat track length determines the length of the design H-point travel path. The seat track length and front/rear of the H-point travel path relative to the X-reference point are given in Table 3 for five levels of driver accommodation. A minimum seat track length of 240 mm, which accommodates 95% of the driving population, is recommended. The end points of the H-point travel path provide a symmetrical disaccommodation, i.e. the same percentage of the driving population is excluded at the front and the rear of the seat track travel.

TABLE 3—SEAT TRACK LENGTH (MM)

Desired Accommodation (%)	Front of H-point travel path from H-point X-reference (mm)	Rear of H-point travel path from H-point X-reference (mm)	Total Seat Track Length (mm)
98% (1-99)	-135	145	280
97.5% (1.3-98.8)	-131	140	271
95% (2.5-97.5)	-116	124	240
90% (5-95)	-100	106	206
80% (10-90)	-79	83	162

5.3 Position H-point Travel Path in Vehicle

To position the design H-point travel path in the vehicle, construct a horizontal line through SgRP whose endpoints are the values for front and rear of the H-point travel given Table 3. For a 240 mm seat track length the endpoints will be 116 mm forward, and 124 mm rear of the H-point X reference calculated in Equation 3.

5.3.1 ADD DRIVER SEAT POSITION ACCOMMODATION POINTS (OPTIONAL)

If desired, points specified in Table 4 may be positioned on the H-point travel path to represent varying levels of driver population accommodation.

TABLE 4—ACCOMMODATION POINTS

Percent Accommodation	1	1.25	2.5	5	10	90	95	97.5	98.75	99
Distance from seat track X-reference (mm)	-135	-131	-116	-100	-79	83	106	124	140	145

5.3.2 ANGLE SEAT TRACK IN SIDE VIEW

Select a design seat track angle (A18). Rotate the H-point travel path and the accommodation points about the SgRP to the design track angle. This line represents the design H-point travel path (Figure 9).

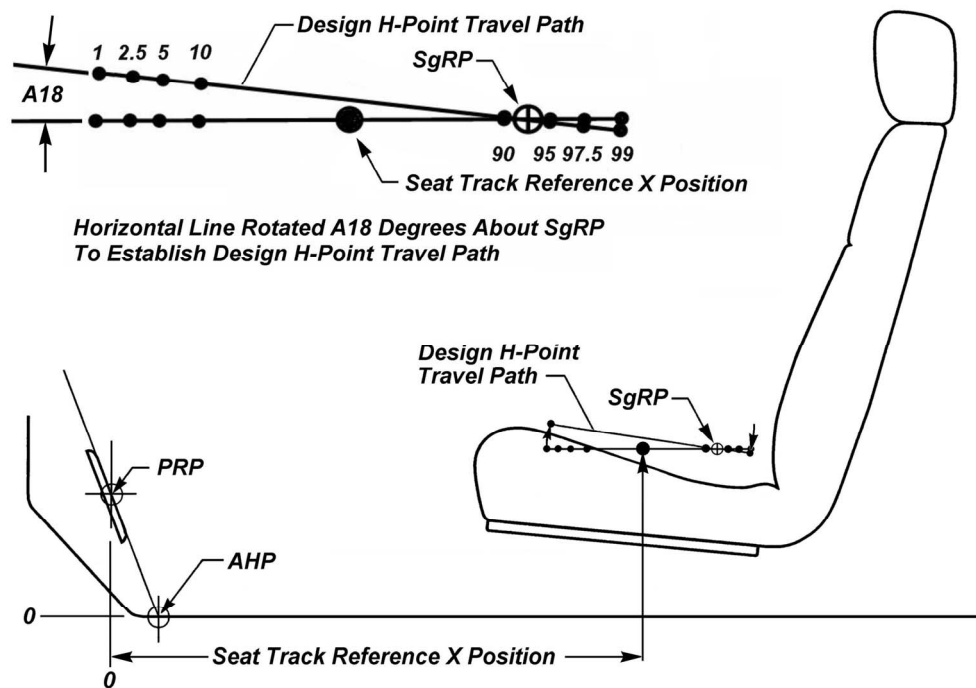


FIGURE 9—EXAMPLE OF DRIVER SEAT POSITION ACCOMMODATION POINTS ON THE DESIGN H-POINT TRAVEL PATH

5.4 Position Seat Track in Vehicle

The seat and seat track shall be positioned in the vehicle so that the H-point moves along the design travel path. For seats with vertical adjustment, the design H-point travel path should be at or near the middle of the vertical adjustment range of the H-point travel path (Figure 7).

6. Design Procedures for 2nd or 3rd Row Outboard Seating Positions

This procedure is used to position reference points in the vehicle's interior space pertaining to passengers, including SgRP (second, third, or fourth, etc.), floor reference points, and floor plane angles. After this procedure is complete, many additional interior dimensions can be measured.

In order to position the HPD properly in a rear seat, the seat directly in front of it must be positioned at its SgRP. In other words, to set up the second row passenger seat, the driver or front passenger seat must be positioned at its SgRP location; to set up the third row passenger seat, the second row passenger seat must be at its SgRP location, etc.

The location of the shoe and the lower leg are specified by this procedure. If a seat with an adjustable recliner is provided, design back (torso) angle is at the manufacturer's discretion. However, a design back (torso) angle of 25 degrees is recommended. If the seat back does not recline that far, then the maximum back (torso) angle is recommended as the design back angle.

SgRP for a rear seat is at the manufacturer's discretion.

6.1 Determine the Initial Target Values

Determine the initial target values for the dimensions listed in Table 5. (See SAE J1100 for definitions.)

TABLE 5—VALUES NEEDED TO POSITION THE HPD FOR PASSENGERS

Dimensions	2 nd Row Codes	3rd Row Codes	Final Values
Seat Height	H30-2 _{Target}	H30-3 _{Target}	Depending on the Z coordinate of the floor reference point defined during this procedure, the final value of seat height might be different. However, if desired and possible, the height of the seat in question can be adjusted to maintain the target value.
Occupant Centerline	W20-2 _{Target}	W20-3 _{Target}	This value is not changed as a consequence of this procedure.
Back (Torso) Angle	A40-2	A40-3	Seats with an adjustable seat back: Manufacturer's discretion (set to maximum back/torso angle, if the maximum is less 25 degrees) Seats without a seat back adjustment: Manufacturer's discretion. A40 is a seat characteristic. It is neither calculated nor modified by this procedure. Rather, it is used to position the attitude of the back pan assembly.
Lumbar Support Prominence	L81-2	L81-3	L81 is a seat characteristic. It is neither calculated nor modified by this procedure. Rather, it is used to posture the back pan articulation, specifying the distance (X) of the lumbar-pelvic pivot (L/P pivot) to the back (torso) line, measured normal to the back line. (See Figure 3.) LSP=57-X mm
Cushion Angle	A27-2	A27-3	A27 is a seat characteristic. It is neither calculated nor modified by this procedure. Rather, it is used to position the attitude of the cushion pan assembly.

6.2 Establish Seat Positions

6.2.1 SEAT POSITION OF SEAT IN FRONT

Position the seat directly in front of the current seat so that the seat in front is at its design intent location and attitude – i.e., the seat H-point is at SgRP, with the seat cushion and seat back set to reflect the correct back (torso) angle and cushion angle.

6.2.2 CURRENT SEAT POSITION

If the seat being assessed is adjustable, position it at its design intent location and attitude. If the seat has an adjustable seat back recliner, set it to design intent. If the maximum back (torso) angle of the seat is less than 25 degrees, set it to the maximum.

6.3 Position HPD (Cushion and Back Pan Assemblies), Determine SgRP

Set the HPD in the seat, while maintaining the desired target values for back (torso) angle, cushion angle and lumbar support prominence. The location of the H-point defines SgRP.

6.4 Position Shoe Tool

Position the shoe tool on the floor with the bottom of shoe contacting the depressed floor covering, normal to the Y plane, so the shoe centerline lies laterally within 127 mm to either side of the occupant centerline. The shoe tool is placed as far forward as possible, based on the understructure and trim surfaces of the seat in front (Figure 10).

Interference above the ankle pivot circumference is not considered for positioning the shoe but will be considered when determining leg and knee clearance with short-coupled seating. Use this shoe position to define the leg room. In the rare case that the shoe does not physically fit between the seats, the rear of the shoe is positioned against the trim under the test seat with the front of the shoe intruding into the preceding seat trim and/or structure (Figure 11).

For long-coupled seating, the shoe has to be moved farther rearward in order to attach and properly position the thigh and lower leg segments. Move the shoe rearward until an ankle angle of 130 degrees is achieved with the thigh assembly attached to the H-point and the lower leg assembly attached to the shoe tool. Use this position to establish the floor reference point, floor plane angle, knee clearance (L48), leg clearance (L58), and all other dimensions except leg room (L51).

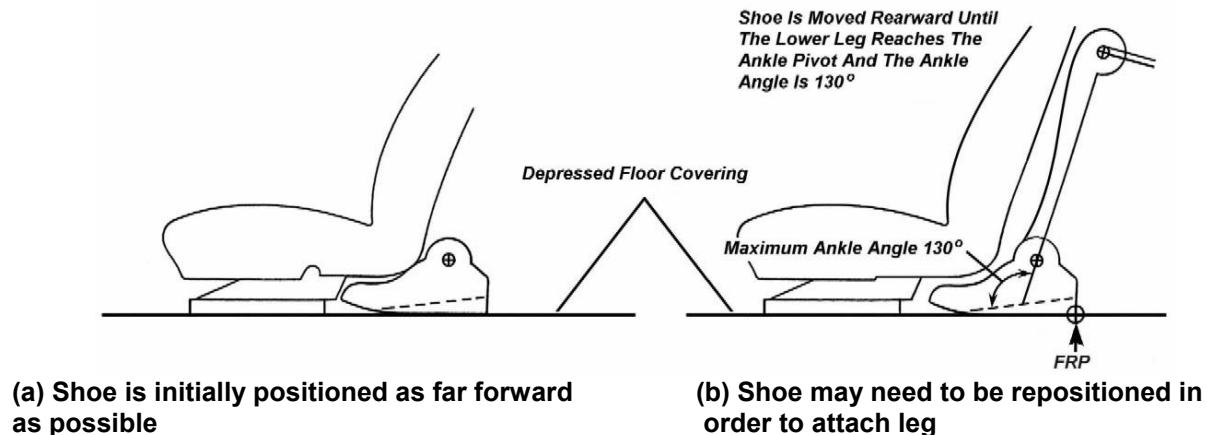


FIGURE 10—FLOOR REFERENCE POINT (FRP)

6.5 Position Thigh and Lower Leg

Use the SgRP leg lengths of 456 mm for thigh and 459 mm for lower leg. Position the legs without moving the shoe tool while keeping the H-point on the SgRP. The thigh rotates about the H-point y-axis connecting the H1L and H1R divot points, and the lower leg rotates about the ankle in order to accomplish this. The y-coordinate of the leg is aligned to the y-coordinate of the heel of shoe (HOS). Lateral splay of the leg is not permitted.

If the preceding seat back does not interfere with the HPM knee or lower leg, measure knee clearance (L48) and leg clearance (L58) as the minimum clearance between the preceding seat back and the knee or lower leg. See SAE J1100.

If the preceding seat back interferes with the lower leg segment above the ankle circumference, proceed according to 6.6 before determining clearances (Figure 12).

6.6 Short-coupled Seating

In vehicles with short-coupled seating the seat back of the preceding seat interferes with the knee or the lower leg segment of the H-point device (Figure 11).

Measure knee clearance (or leg clearance) in CAD using the HPD and CAD data for the seat back in the vicinity of the K1 divot point and lower leg segment. Both measures will be negative values when there are interferences. If the preceding seat back interferes with the knee, knee clearance (L48) is a negative value equal to the measurement from the knee pivot center to the interference minus 51 mm. If the seat back interference is rearward of the knee pivot center add 51mm to the distance from the knee pivot center to the interference.

If the leg interferes with the preceding seat back, leg clearance (L58) is a negative value equal to the amount of maximum interference measured from the front of the lower leg normal to the leg line. See SAE J1100.

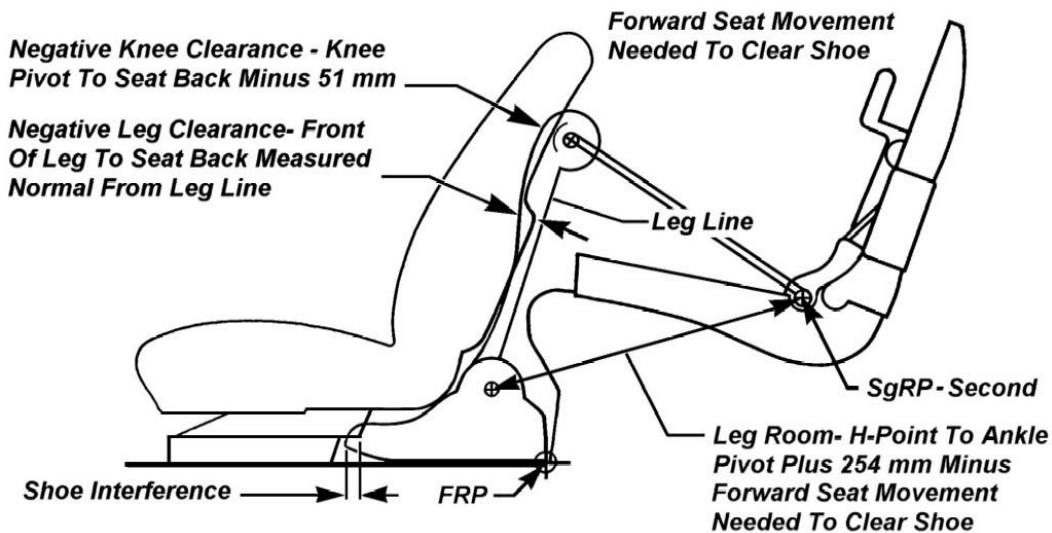


FIGURE 11—SHOE INTERFERENCE, KNEE CLEARANCE AND LEG CLEARANCE FOR SHORT-COUPLED SEATING

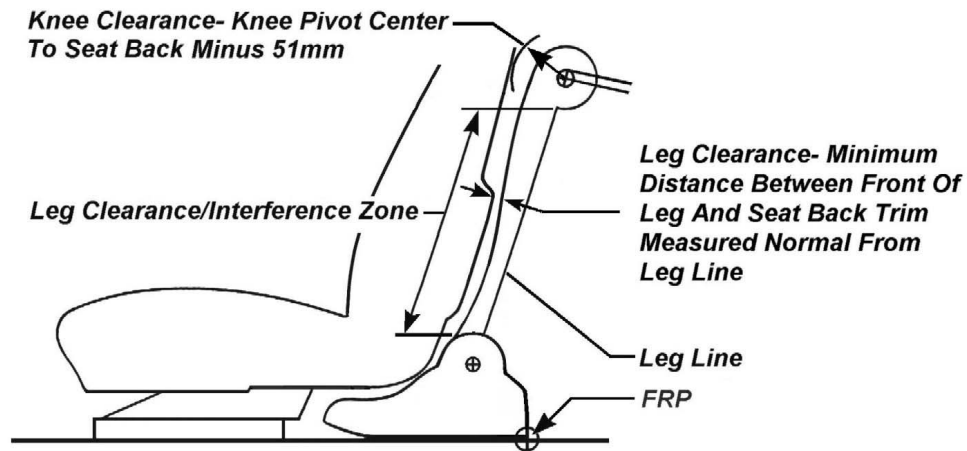


FIGURE 12—KNEE AND LEG CLEARANCE ZONES

6.7 Determine Dimensions

The dimensions listed in Table 6 can now be determined. The FRP is the point on the depressed floor covering contacted by the heel of shoe. The floor plane angle is defined by the shoe tool's attitude. When viewed from the side, the segment from BOF to the heel of the shoe defines the floor plane angle.

TABLE 6—DIMENSIONS (SEE SAE J1100 FOR DEFINITIONS)

SAE J1100 Code ^a	Dimension
L31, W20, H70	SgRP X, Y, and Z coordinates
H30	Seat Height
L98 and H98	Floor Reference Point X and Z coordinates
A48	Floor Plane Angle
A40	Back (torso) Angle
A27	Cushion Angle
A57	Thigh Angle
A42	Hip Angle
A44	Knee Angle
A46	Ankle Angle
L81	LSP
H61	Effective Head Room
L48	Knee Clearance
L58	Leg Clearance
L51	Effective Leg room

a) A suffix (-2, -3, ...) that denotes the seat row must be added to each dimension code.

APPENDIX A
MODEL DESCRIPTION AND APPLICATIONS FOR OTHER DRIVER POPULATIONS

A.1 Background

In this appendix, a more detailed description of the seat position prediction model is described. The complete model provides a method for determining driver seat track length for special cases where seat track lengths are needed for different driver populations (a different stature distribution, gender mix, or percentile accommodation).

SAE J1517 incorporated a driver seat position prediction model that is briefly described in Appendix C. This model was only valid for a 50/50 male/female U.S. driver population. It could not be readily adapted to predict seat position for other driver populations and gender mixes.

The model embodied in J4004 represents a completely different approach to predicting seat position. This model predicts seat position (measured aft of PRP) for an individual driver in a specific vehicle, based on his/her stature and various vehicle parameters. The distribution of seat positions for a particular driver population is then built by applying a population stature distribution to the seat position prediction model.

The data used to develop the present model were collected over several years (2.2.3 and 2.2.6). Preferred seat position was measured for 50 to 120 subjects in 36 vehicles and 18 laboratory buck conditions. In each vehicle, subjects were stratified by stature so that small and large statures were overrepresented for greater accuracy in measuring seat position preference among drivers near the tails of the seat position distribution. Vehicles were selected to span a wide range of vehicle dimensions.

Within each vehicle, seat position was regressed on stature. Across vehicles, seat position was shown to be linearly related to stature, independent of gender and independent of vehicle variables. Thus, an overall slope, intercept, and error estimate (MSE, the mean squared error) were calculated by averaging the values for individual vehicles.

A.2 Model Description

The seat position prediction model in SAE J4004 represents each single-gender seat position distribution using a normal distribution. Data analysis shows that individual seat position is best predicted by stature, regardless of gender. Thus, the relationship between seat position and stature within a vehicle is the same for males and females, so one prediction equation is sufficient. Across vehicles, seat position depends only on vehicle variables, so a single equation can be used to predict the seat position of any individual (male or female) in any vehicle. Equation A1 shows this predictive relationship.

$$X = 16.8 + 0.433 (\text{stature in mm}) - 0.24(H30) - 2.19(A27) + 0.41(L6) - 18.2t \quad (\text{Eq. A1})$$

Because population stature is normally distributed (within gender), and because Equation A1 is linear in stature, the same equation predicts the mean male seat position as a function of the mean male population stature. Similarly, predicted mean female seat position is given by Equation A1 when mean female population stature is entered.

The predicted standard deviations of the male and female seat position distributions can be estimated using Equation A2.

$$s_x = \sqrt{0.433^2 s_h^2 + 29.7^2} \quad (\text{Eq. A2})$$

where,

s_x is the standard deviation of the male or female seat position distribution

s_h is the standard deviation of the male or female stature distribution

Equation A2 represents the basic relationship between the standard deviation of a normally distributed variable and the standard deviation of a linear transformation of that variable. The variance, s_x^2 , of the linear combination (seat position) is equal to the sum of two components of variance. The first is the “explained variance,” which is the slope of the relationship squared (0.433^2) multiplied by the variance of the original distribution (single-gender stature). The second component is the “unexplained variance,” which was obtained from the regression of seat position on stature. That value was estimated to be 29.7.

By substituting the standard deviation of male stature or female stature of the driver population for s_h , Equation A2 provides an estimate of standard deviation of male or female seat position. With mean and standard deviation of seat position, distributions of male and female seat position can be fully described for each vehicle. Figure A1 illustrates these distributions.

Figure A1 also illustrates the way in which driver seat position accommodations are determined from these distributions. The horizontal axis represents seat position aft of PRP. Although males have a more rearward average seat position, the two distributions overlap. As a result, both distributions must be considered when determining the location of fore and aft cutoff points. In Figure A1, the vertical line represents a candidate forward seat position cutoff. The area with vertical hatch marks represents the males who would be unable to sit in their preferred seat position if the front end of the seat track were located at the cutoff. The area with diagonal hatch marks represents the females who would sit forward of the cutoff. The sum of these areas as a proportion of the whole is the total percent of drivers who would be “disaccommodated” by a seat track with its front end located at the vertical cutoff.

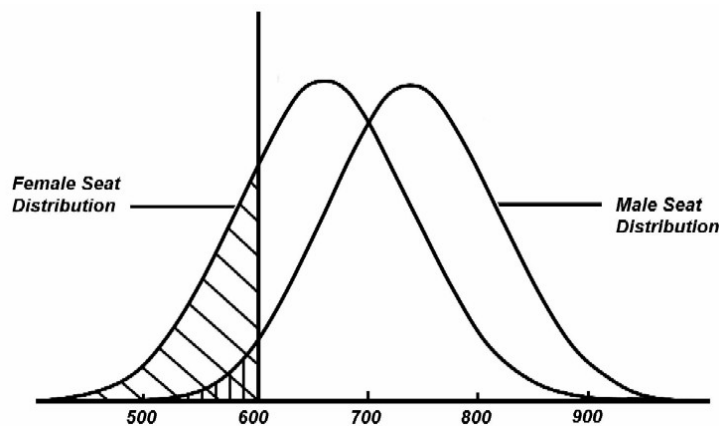


FIGURE A1—ILLUSTRATION OF MALE AND FEMALE SEAT POSITION DISTRIBUTIONS
RELATIVE TO PRP X-COORDINATE

For this application, the desired result is not the percent accommodation for each cutoff, but the cutoff value that corresponds to a given percent accommodation. However, because the cumulative normal distribution is not represented by a closed-form equation, the percent accommodation must be calculated for each cutoff value, and then the results must be searched for the desired accommodation level.

A.3 Tolerance

The seat position prediction model described represents the best estimate of the location and spread of the seat position distribution for a given vehicle, on average. For a 50/50 male/female U.S. driver population, the seat track that accommodates 95% of drivers would be 203 mm long. However, the true distribution will differ from the predicted distribution by some amount in each vehicle. Because the key result of this model is to predict the tails of the distribution, deviations from predicted mean and standard deviation of seat position have asymmetrical impact on accommodation at each tail of the distribution. Figure A2 illustrates the case where the predicted mean seat position is shifted rearward of the true underlying distribution.

In Figure A2, the right distribution represents the predicted distribution, on which seat track placement is based. The left distribution represents the true underlying seat position distribution, which, in this case, is forward of predicted. The tall vertical bars show the front and rear seat track limits, selected on the basis of the predicted seat position distribution. The light gray shading indicates the portion of the population that would have been accommodated if the mean prediction had been perfectly accurate but which is disaccommodated by the seat track placement based on the model. The dark gray shading indicates the portion of the population that would have been disaccommodated by a model with perfectly accurate prediction of the mean, but which is accommodated by the seat track placement based on the model. From this graph, it is clear that the unintentionally disaccommodated group (light shading) is larger than the unintentionally accommodated group (dark shading). A similar effect occurs with misprediction of standard deviation of seat position, but the effect shows up across vehicles, rather than within a single vehicle.

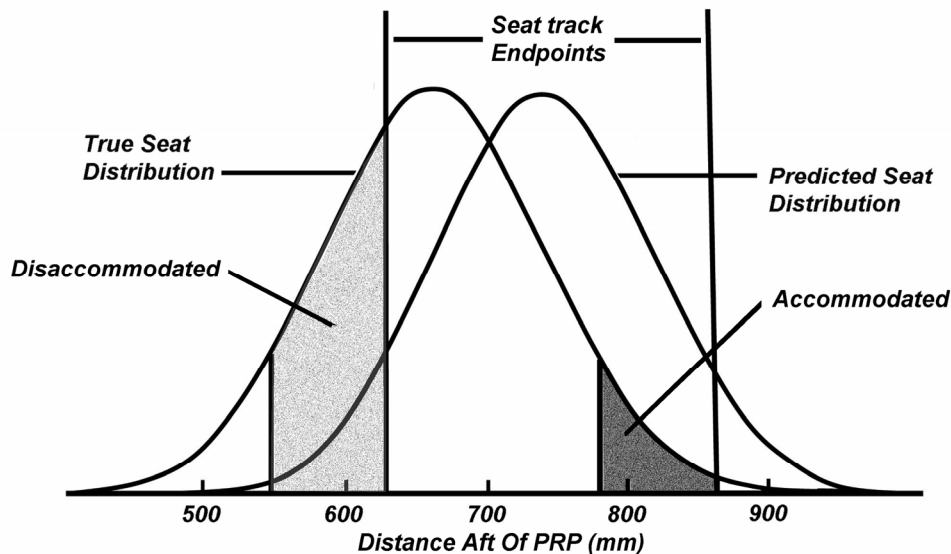


FIGURE A2—ILLUSTRATION OF CONSEQUENCES OF MIS PREDICTION
IN MEAN SEAT POSITION

“Tolerance” is a statistical concept in which limits are determined such that X percent of drivers are accommodated with Y percent certainty. Accommodation is represented by X and tolerance by Y. The model as stated above has less than 50% tolerance because of the asymmetrical disaccommodation effect. To reach higher levels of tolerance, the most straightforward approach is to increase the estimate of random error in the standard deviation. Details are given in the next section.

A.4 Procedure

A.4.1 Define Distributions

The distributions in Figure A1 represent seat position distributions for males and females. Defining these distributions is the first step in determining the seat track length and position that will accommodate the desired percentage of the whole driver population.

The seat position distributions for males and females are normal distributions. Each distribution is defined by its parameters, the mean and standard deviation. Because the effect of stature on seat position is the same for males and females, Equation A1, repeated below, is sufficient to determine the mean of both male and female distributions for a given vehicle. The only difference is the value of mean stature used in solving the equation. Use mean female stature to determine mean female seat position, and use mean male stature to determine mean male seat position.

$$X = 16.8 + 0.433(\text{stature in mm}) - 0.24(H30) - 2.19(A27) + 0.41(L6) - 18.2t \quad (\text{Eq. A1})$$

Similarly, Equation A2 can be used to predict the standard deviation of male and female seat position distributions. Again, the only difference is that the standard deviation of the female stature distribution is used to determine the standard deviation of the female seat position distribution and the standard deviation of the male stature distribution is used to determine the standard deviation of the male seat position distribution.

$$s_x = \sqrt{0.433^2 s_h^2 + 29.7^2} \quad (\text{Eq. A2})$$

A.4.2 Compute Percent Accommodation

Once the two seat position distributions are defined according to A.4.1, the percent of the distribution that lies to the left of each possible cutoff value must be tabulated. The relative proportion of males and females becomes relevant in this step. Equation A3 gives the equation necessary for this step.

$$P(k) = p_m \Phi((k - X_m) / s_m) + (1 - p_f) \Phi((k - X_f) / s_f) \quad (\text{Eq. A3})$$

where,

$P(k)$ is the proportion of the combined male and female population that lies to the left of cutoff k

p_m is the proportion of males in the driver population

p_f is the proportion of females in the driver population

X and s are the mean and standard deviation of seat position, and

Φ is the cumulative normal distribution

Conceptually, Equation A3 translates seat position cutoff (k) into a z-score and determines the proportion of the normal distribution that lies to the left of that z-score for males and females separately. The male and female proportions are then weighted by their relative driving population proportions. The result $P(k)$ is the proportion of drivers who sit forward of the cutoff location. When the cutoff represents the forward endpoint of the seat track, these drivers are not accommodated. In other words, their preferred seat position would lie forward of the available track travel. When the cutoff represents the rearward endpoint of the seat track, these drivers are accommodated (at least in rearward travel), because their preferred seat position lies forward of the rearmost point on the seat track.

A.4.3 Select Cutoff With Desired Accommodation Level

The procedure described in A.4.1 and A.4.2 is repeated for a wide range of possible cutoff values. In order to select the appropriate value, the desired percentiles must be defined for both forward and rearward travel. For typical applications, the user will have a target accommodation level such as 95 percent, and the drivers who are not accommodated will be evenly split between those who sit too far forward and those who sit too far rearward. Thus, the target percentile at the forward end would be 2.5 and the target percentile at the rearward end would be 97.5. However, target accommodation does not have to be symmetrical. A 95% accommodation level could also be achieved with a 1st percentile forward cutoff and a 96th percentile rearward cutoff.

To determine the cutoff for forward travel, the table of possible cutoff values must be searched for the percentile closest to the target for forward travel. The cutoff value that corresponds to the target percentile is the value for the driver population and gender mix for forward travel. The same search procedure is applied to the rear-travel target percentile. The difference between these values is the total seat track travel necessary for the chosen accommodation level.

A.4.4 Incorporate Tolerance

The method described in A.4.1 through A.4.3 generates a seat track that is the best prediction to accommodate the target percent of drivers. However, because of the asymmetrical consequences of errors in prediction described in Section A.3, target accommodation will be achieved in only about 43% of vehicles. In order to achieve the target accommodation level more often, Equation A2, which predicts standard deviation of the seat position distribution must be replaced by Equation A2a.

$$s_x = \sqrt{0.433^2 s_h^2 + e^2} \quad (\text{Eq. A2a})$$

In Equation A2a, the MSE value of 29.7 is replaced by a variable (e) that represents the error component of the predicted standard deviation of seat position. The variable value would typically be greater than 29.7 for greater tolerance. For example, an MSE value of 43.8 gives a tolerance of 88% when the driver population is 50% male. Using this value to generate male and female seat position distributions as described in A.4.1 through A.4.3, a seat track of 240 mm is expected to accommodate 95% of drivers in 88% of vehicles.

Monte Carlo simulations were used to determine the relationship between the estimate of random error used for the model and tolerance level achieved. From these simulations, Equation A4 was developed to determine the tolerance level associated with a particular value of random error. Equation A4 depends only on the gender mix of the driver population, expressed as the percent of males.

$$t = \Phi^{-1}(-3.05 + 0.097e - 2.14|p_m - 0.5| + 0.067e|p_m - 0.5|) \quad (\text{Eq. A4})$$

where,

t is tolerance,

e is the MSE component used to generate male and female seat position distributions,

p_m is the percent of males in the driver population, and

Φ^{-1} is the inverse standard normal distribution

Equation A4 includes the inverse cumulative normal distribution, so it cannot be easily inverted. If the user wants to specify the tolerance level and find the corresponding value of e , then the equation can be solved for many different values of e and the list can be searched for the one that gives the desired tolerance level.

The values given in Table 3 represent a tolerance of 90% for each percent accommodation when the driver population is 50% male.

**APPENDIX B
HPD SPECIFICATION AND TOLERANCES**

B.1 Tolerances

HPD tolerances reflect dimensional variations that may occur when importing and exporting the HPD CAD data into various CAD software programs, because each program may contain default settings that can affect the accuracy of the HPD data. Also, when dealing with curved surfaces, the accuracy of the HPD surface can vary based on the number of sections used to define the surface. HPD tolerances are still being reviewed and may be reduced in the future.

B.2 Reference posture for specifications

Unless otherwise specified, all dimensions in this section are given in true vertical or true horizontal, with the device postured using the settings in Table B1. (See Figure B1.)

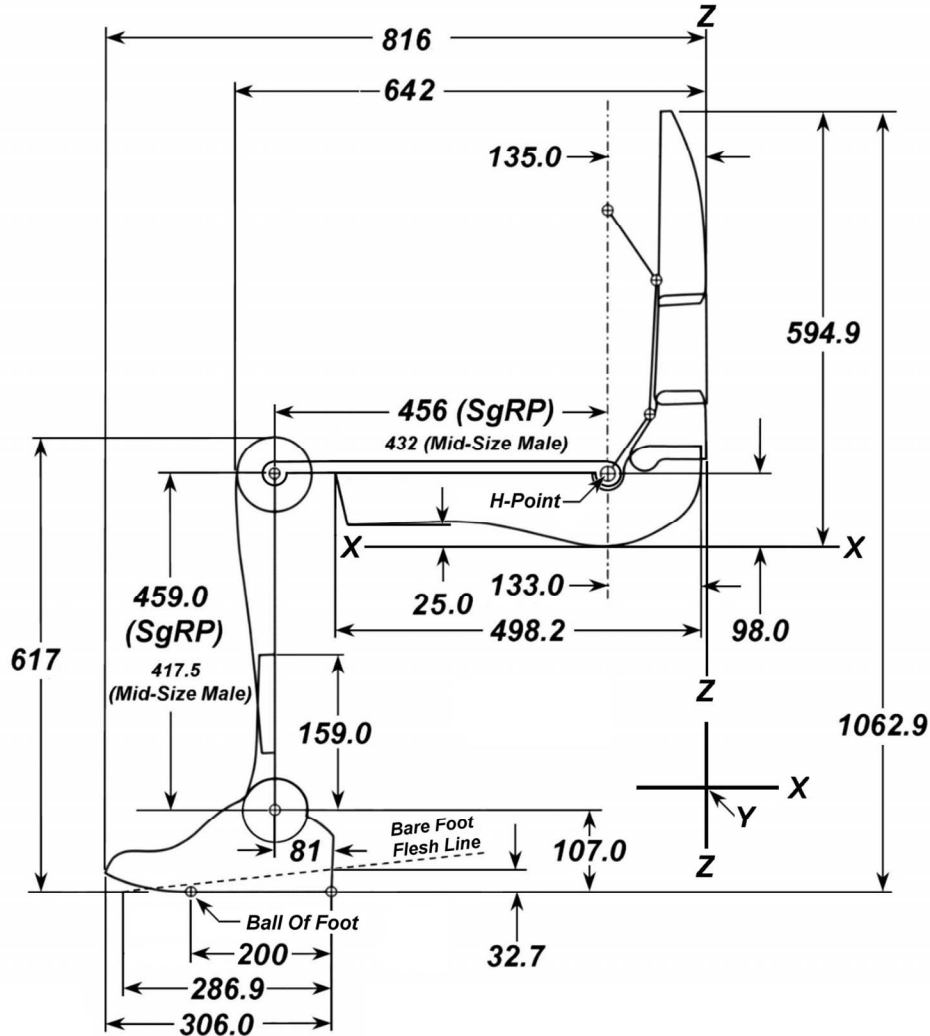


FIGURE B1—HPM LENGTHS AND HEIGHTS, SIDE VIEW

TABLE B1—POSTURE OF DEVICE FOR SPECIFICATIONS

Torso angle	0	degrees
LSP	0	mm
Cushion Angle	0	degrees
Thigh Angle	0	degrees
Knee Angle	90	degrees
Ankle Angle *	96.5	degrees
Thigh Length	456	mm (SgRP)
Lower Leg Length	459	mm (SgRP)

* The bottom of the shoe is flat on the XY plane. However, since ankle angle is measured from the bare foot flesh line, and not the bottom of shoe, the ankle angle will be 96.5 degrees, not 90 degrees.

B.3 Shoe tool dimensions

See Table B2.

TABLE B2—SHOE TOOL DIMENSIONS

Dimension	Value
Overall length of shoe	306 mm
BOF to HOS distance	200 mm
Ankle pivot	107 mm above HOS 81 mm forward of HOS
Bare foot flesh line	6.5 degrees above the bottom of shoe. Originates 286.9 mm forward of HOS.
Relative to BOF	9.9 mm above
Relative to HOS	32.7 mm above

B.4 Lengths

See Table B3 and Figure B1.

TABLE B3—LENGTHS (IN MM)

Description	Value	HPD Tolerance
Overall (rearmost to foremost)	816.0	± 1.0
Overall, not counting shoe	642.0	± 1.0
Cushion Pan	498.2	± 0.5
Shoe	306.0	± 0.2
Heel of Shoe to Ball of Foot	200.0	± 0.01
Heel of Shoe to Ankle Pivot	81.0	± 0.01
Heel of Shoe to Origin of Bare Foot Flesh Line	286.9	± 0.01
H-Point to Knee Pivot	456.0	± 0.01
H-Point to Knee Pivot, w/ mid-size male leg lengths	432.0	± 0.01
H-Point to back of cushion pan	133.0	± 0.5
H-Point to back of back pan	135.0	± 0.5

B.5 Widths

See Table B4.

TABLE B4—WIDTHS (IN MM)

Description	Value	HPD Tolerance
Cushion Pan, Max. (358 mm forward of H-point)	405.8	± 1.0
Cushion Pan, at H-Point	383.3	± 0.5
Cushion Pan, at D-Point	371.0	± 1.0
Cushion Pan, at CP2 support points	401.0	± 1.0
Cushion Pan, at CP3 support points	405.1	± 1.0
Back Pan, Max. (442 mm above H-point)	384.6	± 1.0
Pelvic Segment, at BP1 support point	373.7	± 1.0
Lumbar Segment, at BP2 support point	326.0	± 1.0
Thoracic Segment, at BP3 support point	360.3	± 1.0
Shoe, Max. (at ball of foot)	110.0	± 0.01

B.6 Heights

See Table B5 and Figure B1.

TABLE B5—HEIGHTS (IN MM)

Description	Value	HPD Tolerance
Overall	1062.9	± 1.0
Seated Height (bottom of cushion pan to top of device)	594.9	± 1.0
Cushion Pan, Max.	132.3	± 0.5
Pelvic Segment, Max.	94.9	± 1.0
Lumbar Segment, Max.	150.3	± 1.0
Thoracic Segment, Max.	255.6	± 1.0
Lumbar-Pelvic Pivot to Bottom of Cushion Pan	180.8	± 0.5
Thoracic-Lumbar Pivot to Bottom of Cushion Pan	363.5	± 0.5
H-Point to Bottom of Cushion Pan	98.0	± 0.01
Heel of Shoe to Ankle Pivot	107.0	± 0.01
Heel of Shoe to Bare Foot Flesh Line	32.7	± 0.01
Ball of Foot to Bare Foot Flesh Line	9.9	± 0.01
Knee Pivot Point to Ankle Pivot Point	459.0	± 0.01
Knee Pivot Point to Ankle Pivot Point, mid-size male	417.5	± 0.01
Knee Pivot Point to 'Cross-Over' of Lower Leg Pieces	300.0	± 0.1
Ankle Pivot Point to 'Cross-Over' of Lower Leg Pieces	159.0	± 0.1
Top of Knee to Bottom of Shoe	617.0	± 0.1
Sole of Shoe	3.2	± 0.1

B.7 Radii

The radius of the knee is 51 mm. The radius of the ankle on the shoe tool is 19.1 mm. The radius of the ankle curve at the lower end of the lower leg is 44.5 mm.

B.8 Back pan linkage mechanism

See Table B6. The values provided are straight-line distances, in mm.

TABLE B6—LINKAGE DISTANCES ON HPD (IN MM)

Description	Value	Tolerance	Property
H-Point to Lumbar-Pelvic Pivot	100.0	± 0.01	
Lumbar-Pelvic to Thoracic-Lumbar Pivot	183.0	± 0.01	These values remain constant regardless of posture/LSP setting.
Thoracic-Lumbar Pivot to Sliding Thoracic Pivot	119.0	± 0.01	
H-Point to Sliding Thoracic Pivot	363.24	± 0.01	This value increases as LSP increases, and decreases as LSP decreases.
Upper Reverse Link to Thoracic-Lumbar Pivot	36.5	± 0.01	These values remain constant regardless of LSP. The reverse linkage constrains the movement of the back pan segments.
Lower Reverse Link to Lumbar-Pelvic Pivot	36.5	± 0.01	
Upper to Lower Reverse Link	159.3	± 0.01	

B.9 Support points

Support points are located on the outer surface of the cushion pan (CP) and back pan (BP) contours. See Table B7 and Figure B2.

TABLE B7—SUPPORT POINT LOCATIONS (IN MM)

Point	Quantity	Distance from H-point		
		X ^a	Y	Z ^b
D-point	1	25.5	0.0	-95.2
CP1	1	0.0	0.0	-98.0
CP2	2	-125.0	+/- 80.0	-78.2
CP3	2	-250.0	+/-110.0	-69.2
BP1	1	135.1	0.0	35.0
BP2	1	135.1	0.0	175.0
BP3	2	122.7	+/- 90.0	350.0
HPM Tolerance	All Support Points	± 4.0	± 4.0	± 4.0
HPD Tolerance	All Support Points	± 0.1	± 0.1	± 0.1

^a Positive X values are rearward, negative values are forward of H-point.
^b Positive Z values are above, negative values are below H-point.

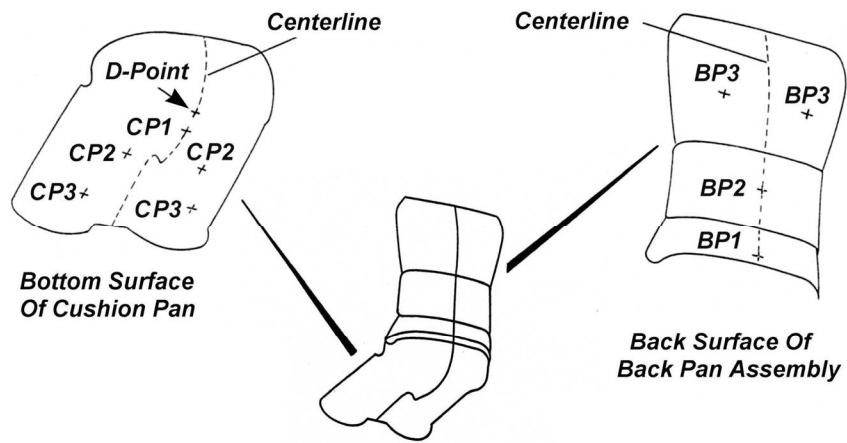


FIGURE B2—SUPPORT POINTS

B.10 Divot point locations

The primary purpose of the divot points is for CMM point-taking on the HPM to allow for the calculation of key reference points in CAD. See Table B8.

TABLE B8—DIVOT POINT LOCATIONS

Divot	Location	HPM Description	HPD Tolerances
B1	550 mm above the H-point on the torso line	Located in the screw hole on the top of the back pan T-handle.	± 0.2
B2	330 mm above the H-point 35 mm forward of the torso line (and H-point).	Located along the back pan centerline, in front of the sliding thorax pivot.	± 0.2
H1L H1R	200 mm to the left (H1L) or the right (H1R) of the measured H-point.	Located at the ends of the rod where the back pan and cushion pan are joined.	± 0.2
C1	275 mm forward of the H-point on the cushion line.	Located along the cushion pan centerline, in a hole on top of the push block.	± 0.2
K1L K1R	239 mm to the left (K1L) or right (K1R) of centerline, on the knee pivot axis.	Used to define the K-point location. The K1L and K1R provide the x, z coordinates, while K2 provides the y coordinate.	± 0.2
K2	50 mm forward of the knee pivot center (K-point)		± 0.1
S1L S1R	(x) 81 mm forward of heel of shoe, (y) +/- 10 mm to either side of the shoe centerline, (z) 107 mm above bottom of shoe.	Located on either side of the ankle pivot. (S1L is 10 mm to the left; S1R is 10 mm to the right.)	± 0.01 (x,y,z)
S2L S2R	(x) 81 mm forward of the heel of shoe, (y) +/- 10 mm to either side of the shoe centerline, (z) 5 mm above bottom of shoe.	Located on top of the sole of the shoe below the ankle pivot. (S2L is 10 mm to the left; S2R is 10 mm to the right.)	± 0.01 (x,y,z)
S3L S3R	(x) 175 mm forward of the heel of shoe, (y) +/- 10 mm to either side of the shoe centerline, (z) 5 mm above bottom of shoe.	Located on top of the sole of the shoe, near the ball of foot. (S3L is 10 mm to the left; S3R is 10 mm to the right.)	± 0.01 (x,y,z)

B.11 File format

The HPD data file is available from SAE, 400 Commonwealth Drive, Warrendale, PA, 15096-0001. Currently, it is only available in the IGES format. The IGES file can be used as a template for creating native geometry within the resident CAD system. (This is recommended.)

B.11.1 Datum lines

To assist the user, other datum lines are provided with the HPD in addition to the reference lines on the HPM. (See Figure 2 and SAE J4002.)

- Lateral centerline of shoe
- Lateral centerline of manikin (through back pan and cushion pan)
- Effective head room line
- Section curves cut through support points
- Additional section curves cut through the cushion and back pans

The additional section curves are provided to convey the size and shape of complex torso geometry. This is a quality assurance measure, and provides an effective way of validating geometry across CAD systems.

APPENDIX C BACKGROUND ON THE PRIOR MODEL OF DRIVER-SELECTED SEAT POSITION

Driver seat position models have been in use for many years. Field studies of the seat positions chosen by representative samples of U.S. drivers, when driving vehicles or seated in package bucks having a variety of vehicle package geometries, were used to develop these models of driver preferred seat positions. The models predict how long seat tracks need to be in order to accommodate a given percentage of drivers.

C.1 SAE J1517 Method

Philippart et al. (2.2.2) used seven regression equations to predict each of seven percentiles of the seat position distribution for a 50/50 male/female U.S. driver population. Each regression equation was fitted to data obtained from empirical percentile values calculated for seat position distributions for each of the 14 vehicles in their database. The fore-aft distance between H-point and accelerator pedal was predicted for each percentile using a second-order function of seat height (H30). This approach directly fitted the data at each percentile, thereby avoiding any assumptions about the form of the seat position distribution. However, its use was restricted to the seven percentiles of a U.S. driver population having a 50/50 male/female ratio for which equations were derived.

This model was used in the SAE J1517 recommended practice for predicting population percentiles of driver-selected seat position (2.2.1) in order to determine seat track length and accommodation. The seven driver seat position accommodation curves (2.5%, 5%, 10%, 50%, 90%, 95%, and 97.5%) are pictured graphically in Figure C1 as a function of the single package variable, seat height (H30).

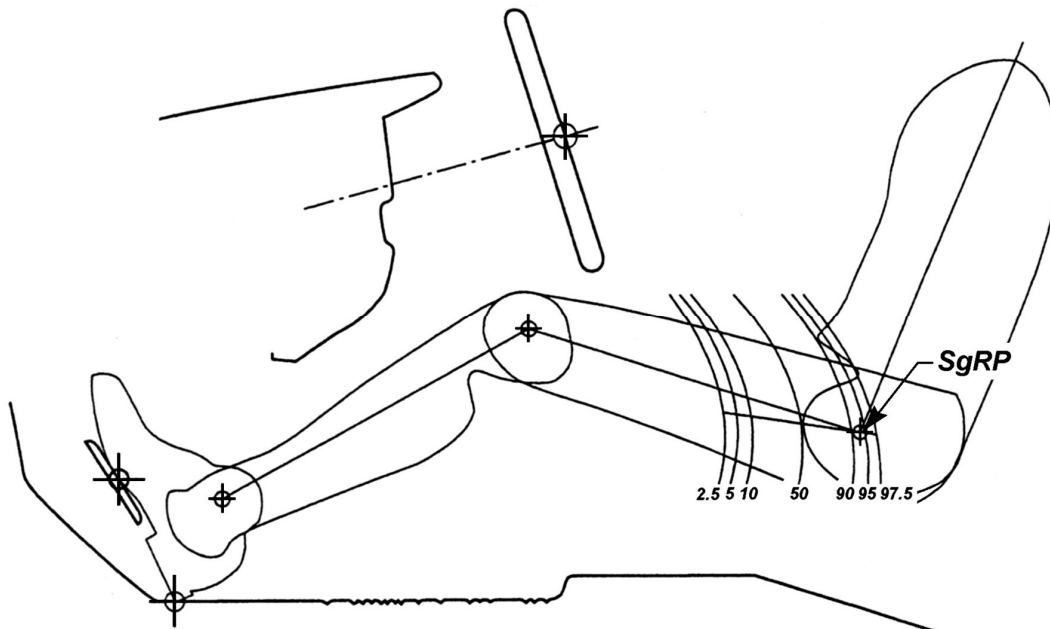


FIGURE C1—DRIVER SELECTED SEAT POSITION MODEL IN SAE J1517 MAR 90

C.2 Key Differences Between Old and New Models

The new model:

- requires longer seat tracks for equivalent accommodation
- provides 90% certainty that seat track length will be sufficient for the specified level of accommodation
- is a linear (not quadratic) function of H30
- incorporates effects of steering wheel, seat cushion angle, and transmission type on driver seat position (These variables influenced driver seat position independently.)
- can be applied to any driver population or gender mix